## TA7

## series



## Product Segments

## - Care Motion

TiMOTION's TA7 is one of the classic linear actuators for medical applications. The TA7's design is compliant with key standards such as IEC60601-1 and ES60601-1.In addition, the TA7 linear actuator is available with an optional IP54, IP66 or IP66W rating. Medical equipment is typical application for the TA7 series linear actuator.

## General Features

| Voltage of motor | 12,24, or 36 V DC |
| :--- | :--- |
| Maximum load | $10,000 \mathrm{~N}$ in push |
| Maximum load | $4,000 \mathrm{~N}$ in pull |
| Maximum speed at full load | $23.4 \mathrm{~mm} / \mathrm{s}$ |
|  | (with $1,000 \mathrm{~N}$ in a push or pull condition) |
| Stroke | $25 \sim 1000 \mathrm{~mm}$ |
| Minimum installation dimension | $\geq$ Stroke +171 mm |
| Color | Black or grey |
| IP rating | Up to IP66W |
| Certificate | IEC60601-1, ES60601-1, IEC60601-1-2, |
|  | EMC |
| Operational temperature range | $+5^{\circ} \mathrm{C} \sim+45^{\circ} \mathrm{C}$ |
| Options | Safety nut, Hall / Reed sensor(s) |

## Drawing

Standard Dimensions
(mm)


Load and Speed


## Motor Speed (2600RPM)

| C | 5000 | 4000 | 5000 | 0.8 | 3.5 | 8.0 | 4.1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| D | 6000 | 4000 | 6000 | 0.8 | 3.5 | 6.0 | 3.1 |
| F | 2500 | 2500 | 2500 | 0.8 | 3.2 | 15.9 | 8.3 |
| G | 2000 | 2000 | 2000 | 0.8 | 2.8 | 21.4 | 12.1 |
| H | 1000 | 1000 | 1000 | 0.8 | 2.1 | 32.1 | 19.1 |
| J | 3500 | 3500 | 3500 | 0.8 | 3.6 | 11.9 | 6.0 |
| K | 8000 | 4000 | 8000 | 0.8 | 4.0 | 5.4 | 2.7 |

Motor Speed (3400RPM)

| $\mathbf{L}$ | 6000 | 4000 | 6000 | 1.0 | 4.2 | 7.3 | 4.1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{N}$ | 2500 | 2500 | 2500 | 1.0 | 4.1 | 19.4 | 11.1 |
| $\mathbf{0}$ | 2000 | 2000 | 2000 | 1.0 | 4.0 | 26.1 | 14.9 |
| $\mathbf{P}$ | 1000 | 1000 | 1000 | 1.0 | 3.0 | 39.0 | 23.4 |
| $\mathbf{0}$ | 3500 | 3500 | 3500 | 1.0 | 4.6 | 14.5 | 7.9 |
| $\mathbf{R}$ | 8000 | 4000 | 8000 | 1.0 | 5.0 | 6.6 | 3.5 |
| $\mathbf{T}$ | 5000 | 4000 | 5000 | 1.0 | 4.2 | 9.8 | 5.4 |

Motor Speed (3800RPM)

| $\mathbf{Y}$ | 8000 | 4000 | 8000 | 1.2 | 5.3 | 7.7 | 4.4 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{B}$ | 10000 | 4000 | 10000 | 1.2 | 5.3 | 5.7 | 3.2 |
| $\mathbf{U}$ | 5000 | 4000 | 5000 | 1.2 | 4.7 | 11.3 | 6.6 |
| $\mathbf{W}$ | 2500 | 2500 | 2500 | 1.2 | 4.6 | 23.0 | 13.4 |
| $\mathbf{Z}$ | 3500 | 3500 | 3500 | 1.2 | 5.3 | 16.8 | 9.8 |

## Note

1 Please refer to the approved drawing for the final authentic value.
2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

3 The current \& speed in table are tested with 24 V DC motor. With a 12 V D motor, the current is approximately twice the current measured in 24 V DC. With a 36 V DC motor, the current is approximately two-thirds the current measured in 24 V DC. Speed will be similar for all the voltages.

4 The current \& speed in table are tested when the actuator is extending under push load.
5 The current \& speed in table and diagram are tested with TiMOTION control boxes, and there will be around $10 \%$ tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32 V DC. At rated load, the voltage output will be around 24 V DC)

6 Standard stroke: Min. $\geq 25 \mathrm{~mm}$, Max. please refer to below table.

| CODE | Load (N) | Max Stroke (mm) |
| :--- | :--- | :--- |
| K, R,Y, B | $\geq 8000$ | 450 |
| D, L | $=6000$ | 600 |
| Others | $<6000$ | 1000 |

Performance Data (24V DC Motor)

Motor Speed (2600RPM)

Speed vs. Thrust


Current vs. Thrust


Speed vs. Thrust


Current vs. Thrust


Performance Data (24V DC Motor)

Motor Speed (3800RPM)

Speed vs. Thrust


Current vs. Thrust


TA7

| Voltage | $1=12 \mathrm{~V} \mathrm{DC}$ | $2=24 \mathrm{~V} \mathrm{DC}$ |
| :--- | :--- | :--- |

Load and Speed See page 2

| Stroke $(\mathbf{m m})$ | See page 2 |
| :--- | :--- |
| Retracted Length <br> $(\mathbf{m m})$ | See page 7 |


| Rear Attachment (mm) | 2 = Aluminum casting, U clevis, slot 6.2, depth 17.0, hole 10.2 |
| :---: | :---: |
|  | 3 = Aluminum casting, U clevis, slot 6.2, depth 17.0, hole 12.2 |
| See page 9 | 4 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2 |
|  | 5 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 12.2 |
|  | $\mathrm{C}=$ Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2, T-bush |

## Front Attachment (mm)

See page 9~10

1 = Punched hole on inner tube + plastic cap, without slot, hole 10.2, with plastic bushing
$2=$ Punched hole on inner tube + plastic cap, without slot, hole 12.2
3 = Plastic, U clevis, slot 8.2, depth 20.2, hole 10.2, for load push < 4000N \& pull < 2500N
4 = Plastic, U clevis, slot 8.2, depth 20.2, hole 12.2, for load push < 4000N \& pull < 2500N
5 = Punched hole on inner tube, without slot, hole 10.2, with plastic bushing
$6=$ Punched hole on inner tube, without slot, hole 12.2
7 = Aluminum casting, U clevis, slot 6.2 , depth 17.0, hole 10.2

8 = Aluminum casting, U clevis, slot 6.2, depth 17.0, hole 12.2

9 = Aluminum casting, U clevis, slot 6.2, depth 17.0, hole 10.2 , with plastic T-bushing
$J=$ Aluminum casting, without slot, hole 10.2 , for dental chair

| Direction of <br> Rear Attachment <br> (Counterclockwise) | $1=0^{\circ}$ | $3=90^{\circ}$ |
| :--- | :--- | :--- |

See page 10

| Color | $1=$ Black | $2=$ Grey (Pantone 428C) |  |  |
| :--- | :--- | :--- | :--- | :--- |
| IP Rating | $1=$ Without | $2=\mid P 54$ | $3=\mid P 66$ | $5=I P 66 \mathrm{~W}$ |


| Special Functions for Spindle SubAssembly | $\begin{aligned} & 0=\text { Without } \\ & 1=\text { Safety nut } \end{aligned}$ | 2 = Standard push only <br> 3 = Standard push only + safety nut |
| :---: | :---: | :---: |
| Functions for Limit Switches <br> See page 10 | 1 = Two switches at full retracted / extended positions to cut current <br> 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal <br> $3=$ Two switches at full retracted / extended positions to send signal <br> 4 = Two switches at full retracted / extended positions to send signal + third one in between to send signal <br> 5 = Two switches at full retracted / extended positions to send signal <br> (Operate with control box: TC1, TC8, TC10, TC14) |  |
| Output Signals | $0=$ Without $\quad 1=$ Hall sensor * 1 | 2 = Hall sensor *2 3 = Reed Sensor |
| Connector | 1 = DIN 6P, $90^{\circ}$ plug | $\mathrm{E}=$ Molex 8P, plug |
| See page 11 | $\begin{aligned} & 2=\text { Tinned leads } \\ & 4=\text { Big 01P, plug } \\ & C= Y \text { cable (For direct cut system, water proof, anti pull) } \\ & D=\text { Extension cable, not preset on motor cover } \\ & \text { (Cable legth } 120 \mathrm{~mm} \text { ) } \\ & \text { R }=\text { Extension cable, preset on motor cover } \\ & \text { (Cable legth 50mm) } \end{aligned}$ | $F=$ DIN $6 P, 180^{\circ}$ plug, for TEC extension cable standard option <br> $M=$ DIN 4P, dental chair plug (40510-143, standard) <br> $N=$ DIN 4P, dental chair plug (40510-040) <br> $\mathrm{G}=$ Audio plug |
| Cable Length | $0=$ Straight, 100 mm $3=$ Straight, 1000 mm <br> $1=$ Straight, 500 mm $4=$ Straight, 1250 mm <br> $2=$ Straight, 750 mm $5=$ Straight, 1500 mm | $6=$ Straight, 2000 mm B $\sim H=$ For direct cut system <br> $7=$ Curly, 200 mm See page 11 <br> $8=$ Curly, 400 mm  |

## TA7 Ordering Key Appendix

## Retracted Length (mm)

1. Calculate $A+B+C=Y$
2. Retracted length needs to $\geq$ Stroke $+Y$

| A. Front Attachment |  |
| :--- | :--- |
| CODE |  |
| $\mathbf{1 , 2 , 5 , 6}$ | +171 |
| $\mathbf{3 , 4}$ | +192 |
| $\mathbf{7 , 8 , 9}$ | +183 |
| $\mathbf{J}$ | +172 |

## B. Load V.S. Stroke

## Stroke (mm) Load (N)

|  | <6000 | $=6000$ | $=8000$ | $=10000$ |
| :---: | :---: | :---: | :---: | :---: |
| 25~150 | - | - | - | +5 |
| 151~200 | - | - | +5 | +10 |
| 201~250 | - | +5 | +10 | +15 |
| 251~300 | - | +10 | +15 | +20 |
| 301~350 | +5 | +15 | +20 | +25 |
| 351~400 | +10 | +20 | +25 | +30 |
| 401~450 | +15 | +25 | +30 | +35 |
| 451~500 | +20 | +30 | - | - |
| 501~550 | +25 | +35 | - | - |
| 551~600 | +30 | +40 | - | - |
| 601~650 | +35 | - | - | - |
| 651~700 | +40 | - | - | - |
| 701~750 | +45 | - | - | - |
| 751~800 | +50 | - | - | - |
| 801~850 | +55 | - | - | - |
| 851~900 | +60 | - | - | - |
| 901~950 | +65 | - | - | - |
| 951~1000 | +70 | - | - | - |

## C. Front Attachment V.S Special Function

Front Spindle Function
Attachment
0,1
2, 3

Load (N) < 6000
$\mathbf{1 , 2 , 5} 6 \quad+5$
3, 4
7,8,9
J
Load (N) $\mathbf{6 0 0 0}$
1, 2, 5, $6 \quad+8$
3, 4
7,8,9 - +3
J

## Rear Attachment (mm)

2 = Aluminum casting, U clevis, slot
6.2, depth 17.0, hole 10.2

$\mathrm{C}=$ Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2, T-bush


3 = Aluminum casting, U clevis, slot 6.2 , depth 17.0 , hole 12.2


4 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2


5 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 12.2


## Front Attachment (mm)

$1=$ Punched hole on inner tube + plastic cap, without slot, hole 10.2, with plastic bushing

$\varnothing 10.2$


5 = Punched hole on inner tube, without slot, hole 10.2, with plastic bushing


2 = Punched hole on inner tube + plastic cap, without slot, hole 12.2

$\varnothing 12.2$

$6=$ Punched hole on inner tube, without slot, hole 12.2


3 = Plastic, U clevis, slot 8.2, depth 20.2, hole 10.2, for load push < 4000N \& pull < 2500N


7 = Aluminum casting, U clevis, slot 6.2 , depth 17.0 , hole 10.2


4 = Plastic, U clevis, slot 8.2, depth 20.2, hole 12.2, for load push < 4000N \& pull < 2500N


8 = Aluminum casting, U clevis, slot 6.2, depth 17.0, hole 12.2


## Front Attachment (mm)

9 = Aluminum casting, U clevis, slot 6.2 , depth 17.0, hole 10.2, with plastic T-bushing

$J=$ Aluminum casting, without slot, hole 10.2, for dental chair


## Direction of Rear Attachment (Counterclockwise)

$1=0^{\circ}$


$$
3=90^{\circ}
$$



## Functions for Limit Switches

## Wire Definitions

| CODE | Pin |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 (Green) | 2 (Red) | 3 (White) | 4 (Black) | 5 (Yellow) | 6 (Blue) |
| 1 | extend (VDC+) | N/A | N/A | N/A | retract (VDC+) | N/A |
| 2 | extend (VDC+) | N/A | middle switch pin B | middle switch pin A | retract (VDC+) | N/A |
| 3 | extend (VDC+) | common | upper limit switch | N/A | retract (VDC+) | lower limit switch |
| 4 | extend (VDC+) | common | upper limit switch | medium limit switch | retract (VDC+) | lower limit switch |
| 5 | extend (VDC+) | N/A | upper limit switch | common | retract (VDC+) | lower limit switch |

## Connector

$1=$ DIN $6 P, 90^{\circ}$ plug

$2=$ Tinned leads

$4=$ Big 01P, plug

$C=Y$ cable (For direct cut system, water proof, anti pull)


| Cable length for direct cut system (mm) |  |  |  |
| :--- | :--- | :--- | :--- |
| CODE | L 1 | L 2 | L 3 |
| B | 100 | 100 | 100 |
| C | 100 | 1000 | 400 |
| D | 100 | 2700 | 500 |
| E | 1000 | 100 | 100 |
| F | 100 | 600 | 1000 |
| G | 1500 | 1000 | 1000 |
| H | 100 | 100 | 1200 |

$\mathrm{D}=$ Extension cable, not preset on motor cover (Cable legth 120 mm )

$R=$ Extension cable, preset on motor
cover (Cable legth 50 mm )

$N=$ DIN 4P, dental chair plug (40510040)

$E=$ Molex 8P, plug

$\mathrm{G}=$ Audio plug


## Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.

