## TA9

## series



## - Comfort Motion <br> - Ergo Motion

TiMOTION's TA9 is one of the smart furniture actuator options with compact dimension. This linear actuator is designed with a custom gear box, molded with a specially formulated plastic material which allows the TA9 to support load ratings up to 2500 N . An EMC certification has been attained for this series, which is also available with optional IP54 or IP66 protection.

## General Features

| Voltage of motor | $12,24 \mathrm{~V}$ DC or 24 V DC (PTC) |
| :--- | :--- |
| Maximum load | $2,500 \mathrm{~N}$ in push |
| Maximum load | $1,000 \mathrm{~N}$ in pull |
| Maximum speed at full load | $30 \mathrm{~mm} / \mathrm{s}$ |
|  | (with 500 N in a push or pull condition) |
| Stroke | $\geq 20 \sim 600 \mathrm{~mm}$ |
| Minimum installation dimension | $\geq$ Stroke +140 mm |
| Color | Black or grey |
| IP rating | Up to IP66 |
| Certificate | IEC60601-1, ES60601-1, IEC60601-1-2, |
|  | UL962, EMC |
| Operational temperature range | $+5^{\circ} \mathrm{C} \sim+45^{\circ} \mathrm{C}$ |
| Options | Hall sensors |

Drawing

Standard Dimensions
(mm)


Load and Speed

| CODE | Load (N) |  | Self Locking | Typical Current (A) | Typical Speed (mm/s) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | Push | Pull | Force (N) | No Load | With Load | No Load | With Load

Motor Speed (4100RPM, Duty Cycle 10\%)

| A | 2000 | 1000 | 2000 | 1.0 | 2.5 | 9.4 | 5.0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| B | 1500 | 1000 | 1500 | 1.0 | 2.5 | 13.8 | 6.8 |
| C | 1000 | 1000 | 1000 | 1.0 | 3.0 | 26.1 | 11.6 |
| D | 800 | 800 | 800 | 1.0 | 2.8 | 36.9 | 16.6 |
| F | 500 | 500 | 500 | 1.0 | 2.8 | 58.3 | 30.0 |

Motor Speed (3800RPM, Duty Cycle 10\%)

| $\mathbf{G}$ | 2500 | 1000 | 2500 | 1.1 | 2.7 | 9.3 | 5.1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{H}$ | 2000 | 1000 | 2000 | 1.1 | 2.9 | 13.2 | 7.0 |
| $\mathbf{I}$ | 1500 | 1000 | 1500 | 1.1 | 3.5 | 26.0 | 12.5 |
| $\mathbf{K}$ | 1000 | 1000 | 1000 | 1.1 | 3.2 | 36.5 | 17.8 |
| $\mathbf{L}$ | 700 | 700 | 700 | 1.1 | 3.2 | 56.5 | 24.2 |

Motor Speed (3400RPM, Duty Cycle 10\%)

| $\mathbf{M}$ | 1500 | 1000 | 1500 | 0.8 | 1.6 | 8.1 | 3.8 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{N}$ | 1000 | 1000 | 1000 | 0.8 | 1.4 | 11.6 | 5.9 |
| $\mathbf{O}$ | 500 | 500 | 500 | 0.8 | 1.4 | 21.9 | 11.3 |
| $\mathbf{P}$ | 400 | 400 | 400 | 0.8 | 1.4 | 30.0 | 15.5 |
| $\mathbf{0}$ | 300 | 300 | 300 | 0.8 | 1.4 | 46.5 | 24.0 |
| Motor Speed (2200RPM, Duty Cycle 10\%) |  |  |  |  |  |  |  |
| V | 2000 | 1000 | 2000 | 0.8 | 1.4 | 5.6 | 2.6 |
| R | 1500 | 1000 | 1500 | 0.8 | 1.4 | 8.1 | 3.7 |
| S | 1000 | 1000 | 1000 | 0.8 | 1.5 | 16.5 | 6.9 |
| T | 800 | 800 | 800 | 0.8 | 1.4 | 22.5 | 10.0 |
| U | 500 | 300 | 500 | 0.8 | 1.4 | 35.5 | 15.6 |

## Note

1 Please refer to the approved drawing for the final authentic value.
2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

3 The current \& speed in table are tested with 24V DC motor. With a 12 V DC motor, the current is approximately twice the current measured in 24 V DC; speed will be similar for both voltages.

4 The current \& speed in table are tested when the actuator is extending under push load.
5 The current \& speed in table and diagram are tested with TiMOTION control boxes, and there will be around $10 \%$ tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32 V DC. At rated load, the voltage output will be around 24 V DC)

6 Standard stroke: Min. $\geq 20 \mathrm{~mm}$, Max. please refer to below table.

| CODE | Load (N) | Max Stroke (mm) |
| :--- | :--- | :--- |
| C, D, F, K, L, N, O, P, O, S, T, U | $\leq 1000$ | 600 |
| B, I, M, R | $\leq 1500$ | 500 |
| A, H, V | $\leq 2000$ | 450 |
| G | $\leq 2500$ | 400 |

Performance Data (24V DC Motor)

Motor Speed (4100RPM, Duty Cycle 10\%)

Speed vs. Thrust


Current vs. Thrust


Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10\%)

Speed vs. Thrust


Current vs. Thrust


Performance Data (24V DC Motor)

Motor Speed (3400RPM, Duty Cycle 10\%)

Speed vs. Thrust


Current vs. Thrust


Performance Data (24V DC Motor)

Motor Speed (2200RPM, Duty Cycle 10\%)


Current vs. Thrust


TA9

| Voltage | $1=12 \mathrm{~V} \mathrm{DC}$ | $2=24 \mathrm{~V} \mathrm{DC}$ | $5=24 \mathrm{~V} \mathrm{DC} PTC$, |
| :--- | :--- | :--- | :--- |
| Load and Speed | See page 3 |  |  |

## Stroke (mm)

## Retracted Length

(mm)

See page 9
Rear Attachment $\quad 1=$ Plastic, U clevis, slot 5.2, depth 13.0, hole 8.0, with plastic T-busing
$(\mathbf{m m})$


See page 10

| Color | 1 = Black | 2 = Grey (Pantone |  |
| :---: | :---: | :---: | :---: |
| IP Rating | 1 = Without | $2=1$ P54 | 3 = P966 |
| Special Functions for Spindle SubAssembly | $0=$ Without (standard) | 2 = Standard push |  |
| Functions for Limit Switches See page 11 | $1=$ Two switches at full retracted / extended positions to cut current <br> 2 = Two switches at full retracted / extended positions to cut current +3 rd LS to send signal <br> 3 = Two switches at full retracted / extended positions to send signal <br> 4 = Two switches at full retracted / extended positions to send signal + 3rd LS to send signal |  |  |
| Output Signal | $0=$ Without | 5 = Hall sensor * 2 |  |
| Connector | 1 = DIN 6P, 90 ${ }^{\circ}$ plug |  | $\mathrm{C}=\mathrm{Y}$ cable ( for direct cut system, water proof, anti pull) |
| See page 11 | $\begin{aligned} & 2 \text { = Tinned leads } \\ & 4=\text { Big 01P, plug } \end{aligned}$ |  | $\mathrm{E}=$ Molex 8P, plug |
| Cable Length (mm) | $\begin{aligned} & 0=\text { Straight, } 100 \\ & 1=\text { Straight, } 500 \\ & 2=\text { Straight, } 750 \end{aligned}$ | $\begin{aligned} & 3=\text { Straight, } 1000 \\ & 4=\text { Straight, } 1250 \\ & 5=\text { Straight, } 1500 \end{aligned}$ | $\begin{array}{ll} 6=\text { Straight, } 2000 & \text { B } \sim \text { H F For direct cut system } \\ 7=\text { Coiled, } 200 & \\ 8=\text { Coiled, } 400 & \end{array}$ |

## TA9 Ordering Key Appendix

## Retracted Length (mm)

1. Calculate $A+B=Y$
2. Retracted length needs to $\geq$ Stroke $+Y$

## A. Front Attach.

| $\mathbf{1 , 2}$ | +140 |
| :--- | :--- |
| $\mathbf{3 , 4}$ | +153 |


| B. Stroke (mm) |  |
| :--- | :--- |
| $\mathbf{2 0 \sim 2 0 0}$ | - |
| 201~250 | +5 |
| $\mathbf{2 5 1 \sim 3 0 0}$ | +10 |
| $\mathbf{3 0 1 \sim 3 5 0}$ | +15 |
| $\mathbf{3 5 1 \sim 4 0 0}$ | +20 |
| $\mathbf{4 0 1 \sim 4 5 0}$ | +25 |
| $\mathbf{4 5 1 \sim 5 0 0}$ | +30 |
| $\mathbf{5 0 1 \sim 5 5 0}$ | +35 |
| $\mathbf{5 5 1 \sim 6 0 0}$ | +40 |

## Rear Attachment (mm)

1 = Plastic, U clevis, slot 5.2, depth
13.0, hole 8.0, with plastic

T-busing


## Front Attachment (mm)

$1=$ Aluminum casting, no slot, hole 8.0

$\varnothing 8$


3 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 8.0


4 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 10.0


## Direction of Rear Attachment (Counterclockwise)

$1=0^{\circ}$


$$
2=90^{\circ}
$$



## TA9 Ordering Key Appendix

## Functions for Limit Switches

## Wire Definitions

| CODE | Pin |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 (Green) | 2 (Red) | 3 (White) | 4 (Black) | 5 (Yellow) | 6 (Blue) |
| 1 | extend (VDC+) | N/A | N/A | N/A | retract (VDC+) | N/A |
| 2 | extend (VDC+) | N/A | middle switch pin $B$ | middle switch pin A | retract (VDC+) | N/A |
| 3 | extend (VDC+) | common | upper limit switch | N/A | retract (VDC+) | lower limit switch |
| 4 | extend (VDC+) | common | upper limit switch | medium limit switch | retract (VDC+) | lower limit switch |

## Connector

$1=$ DIN 6 P, $90^{\circ}$ plug
$2=$ Tinned leads

$4=$ Big 01P, plug

$C=Y$ cable (For direct cut system, water proof, anti pull)


| Cable length for direct cut system $(\mathbf{m m})$ |  |  |  |
| :--- | :--- | :--- | :--- |
| CODE | L 1 | L 2 | L 3 |
| B | 100 | 100 | 100 |
| C | 100 | 1000 | 400 |
| D | 100 | 2700 | 500 |
| E | 1000 | 100 | 100 |
| F | 100 | 600 | 1000 |
| G | 1500 | 1000 | 1000 |
| H | 100 | 100 | 1200 |

$E=$ Molex 8P, plug


## Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.

